Status and Plan of STCF Software

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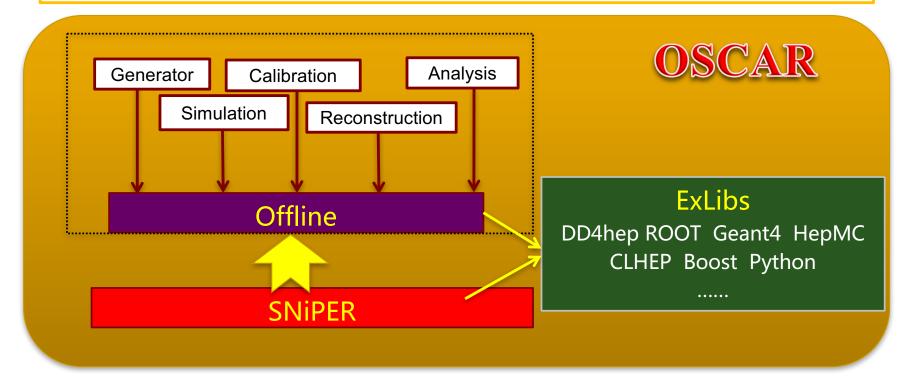
Outline



- STCF Offline Software System
- Framework
- Event Data Model
- Generator
- Detector Simulation
- Visualization
- Reconstruction
- Summary and Outlook

Overview of STCF Software System

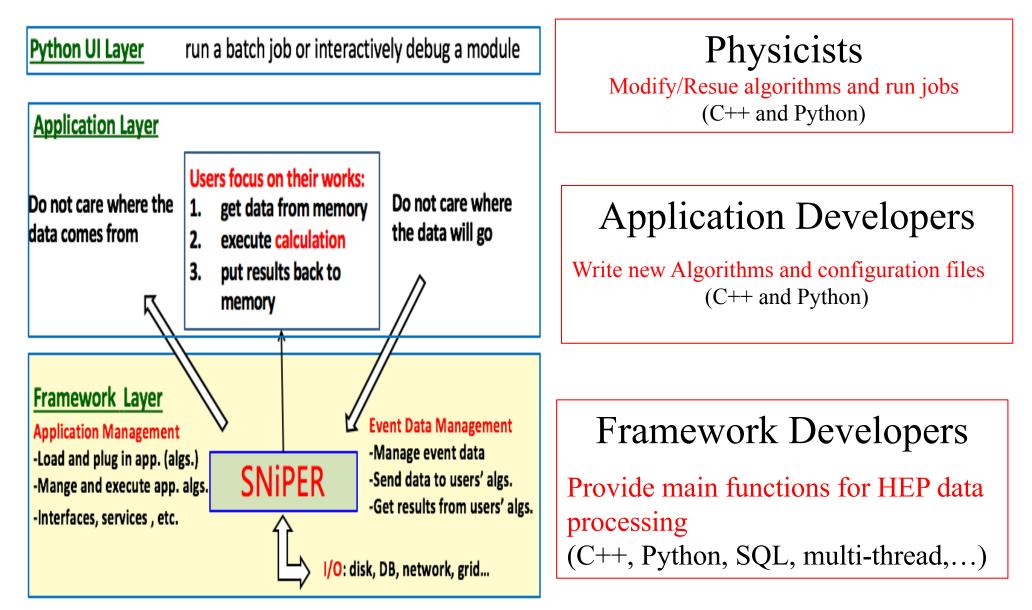
OSCAR: Offline Software of Super Tau-Charm Facility



- **External Libs:** Frequently used third-party software and tools.
- SNiPER Framework: Providing Data Processing Management, Event data Management, Common Services, User Interface ...
- Offline : Specific to the STCF Experiment, including extensions to SNiPER, Generator, Simulation, Calibration, Reconstruction and Analysis

Minimum Requirements of Users





SNiPER Framework



• SNiPER: the "Software for Non-collider Physics ExpeRiment"

- Developed for JUNO experiment ,also considered for other physics experiments
- ⇒Used by JUNO,LHAASO ,STCF, nEXO
- ⇒ Being Investigated by HERD
- The Design Goals
 - ⇒Lightweight, less dependences on third-party software/libs
 - ⇒ Fast and flexible execution
 - ⇒Easy to learn and convenient to use
- ◆ A Good Team to maintain and optimize
 ⇒ SDU and IHEP

Main Features of SNiPER

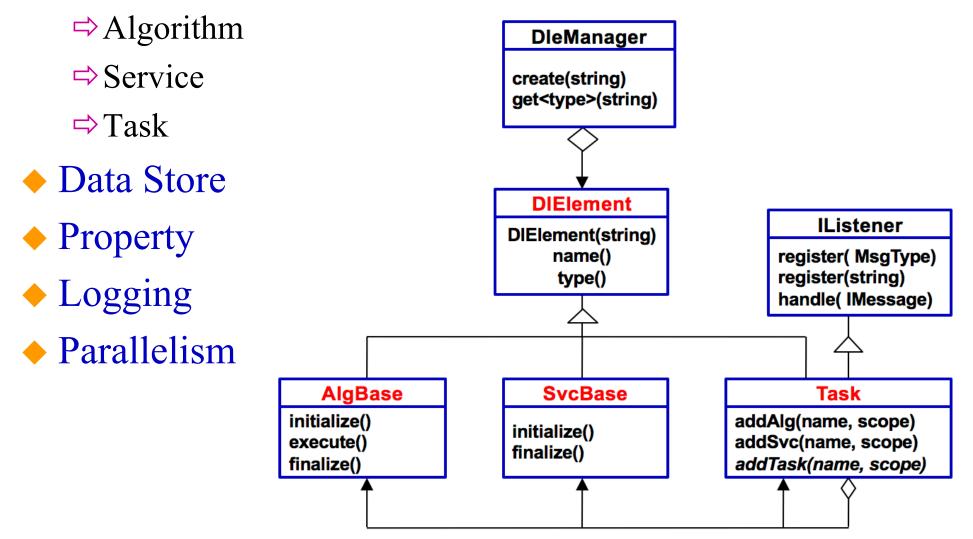


- Highly modular
- Dynamically loading packages/modules/elements
- Standard interfaces between different modules
- Separation between data and algorithm
- Data Store for event data management
- Flexible event execution
 - ⇒ Sequential and Jump/nested execution
- Support multithreading
 - ⇒ Underlying the intel TBB is deployed

Key Components of SNiPER



User Interfaces (Dynamically Loadable Elements)



Algorithm



An unit of code for event execution
 ⇒ Perform event calculation during event loop
 ⇒ Users only focus on processing "One Event"

Framework provides the interface, AlgBase

User's new algorithm inherits from AlgBase

⇒ Its constructor takes one std::string parameter

⇒3 member functions must be implemented

- **bool initialize()** : called once per Task (at the beginning of a Task)
- bool execute() : called once per Event
- **bool finalize()** : called once per Task (at the end of Task)

Then, the new algorithms can be called by Framework

Example: HelloAlg



7	class	HelloAlg: <pre>public AlgBase {</pre>
8		
9	pu	blic:
10		<pre>HelloAlg(const std::string& name);</pre>
11		~HelloAlg();
12		
13		<pre>bool initialize();</pre>
14		<pre>bool execute();</pre>
15		<pre>bool finalize();</pre>
16		
17	pr	ivate:
18		<pre>int m_count;</pre>
19		<pre>std::string m_string;</pre>
20		
21	};	

Service



Similar with Algorithm, but

- ⇒ A piece of code for common use, i.e. GeometrySvc, DatabaseSvc...
- ⇒ They are called by algorithms or other services, wherever needed
- Framework provides the interface, SvcBase
- New services inherits from SvcBase
 - ⇒ Its constructor takes one std::string parameter
 - \Rightarrow 2 member functions must be implemented
 - **bool initialize()** : called once per Task (at the beginning of a Task)
 - bool finalize() : called once per Task (at the end of Task)





7	class H	elloSvc:	public	SvcBa	se {					
8										
9	public:									
10	<pre>HelloSvc(const std::string& name);</pre>									
11		~HelloS	vc();							
12										
13		bool in	itialize	e();						
14		bool fi	nalize()	;						
15		void do	Somethir	ng();						
16										
17	};									

Existing Services



- Data Store Management Service
- Detector Geometry Construction Service
- Unified Geometry Provider Service
- Random Number Service
- Database Service
- Root File Input/Output Service
- Root Histogram/N-tuple Service

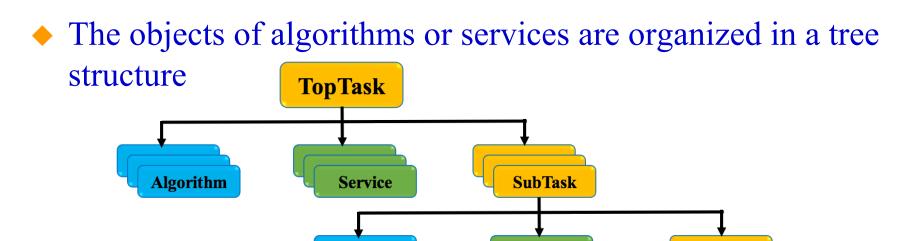


Task



A lightweight application manager

- ⇔Consist of algorithms, services and sub-tasks
- ⇒Control algorithms' execution
- ⇒ Has its own data store and I/O system (see next slide)
- One job can have more than one Tasks



Service

SubTask

Algorithm

13





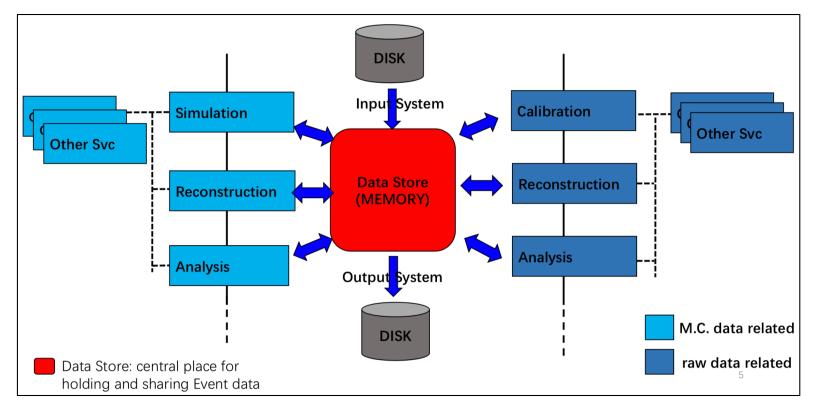
```
4 import Sniper
```

```
5
 6 task = Sniper.Task("task")
   #task.asTop()
   task.setLogLevel(3)
 8
 9
10 import HelloWorld
11 alg = task.createAlg("HelloAlg/hAlg")
   alg.property("VarString").set("some value")
12
   alg.createTool("HelloTool/htool")
13
14
15 svc = task.createSvc("HelloSvc/hSvc")
16
   task.setEvtMax(5)
17
18 task.show()
19 task.run()
```

Data Store



- It is the dynamically allocated memory place to hold event(s) which are being processed
- Algorithms get event data from the Data Store and update/add event data after executions



Interfaces for access to Data Store



 DataStoreMgr is to adopt Event Data in DataStore under a certain path

simHeader->setEvent(simEvent);
SniperPtr<IDataStoreMgr> mMgr(getParent(), "DataStoreMgr");
mMgr->adopt(simHeader, "/Event");

simEvent->setNtracks(m_iEvt);

 EvtDataPtr is to retreive Event Data from DataStore with a unique path

EvtDataPtr<OSCAR::StcfGenHeader> edp(this->getRoot(),"/Event/StcfGenEvent");
OSCAR::StcfGenHeader* header = edp.data();
OSCAR::StcfGenEvent* event = header->event();
event->pEvt()->print();

Property :set parameters at runtime

- Configurable variable at run time
- Declare a property in DLElement(Alg, Svc, Tool and Task)

//suppose m_str is a string data member
declProp("MyString", m_str);

Configure a property in Python script

alg.property("MyString").set("string value")

- Types can be declared as properties:
 - ⇒ scalar: C++ build in types and std::string
 - ⇒ std::vector with scalar element type
 - ⇒ std::map with scalar key type and scalar value type

Logging : manage output message



SniperLog: a simple log mechanism supports different output levels

0: LogTest	LogDebug << "A debug message" << std::endl;
2: LogDebug	LogInfo << "An info message" << std::endl;
3: LogInfo	<pre>LogError << "An error message" << std::endl;</pre>
4: LogWarn	aHelloAlg.execute DEBUG: A debug message
5: LogError	aHelloAlg.execute INFO: An info message
6: LogFatal	aHelloAlg.execute ERROR: An error message

Each DLElement(Alg,Svc,Tool, Task) has its own LogLevel and can be set at run time

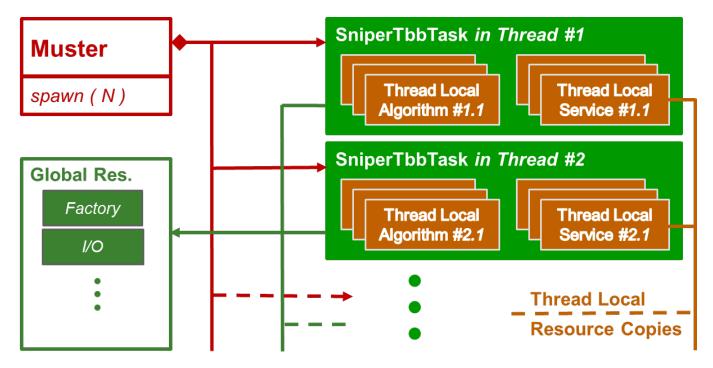
⇒ very helpful for debugging

The output message includes more information , such as

- ⇒ where it happens
- ➡ message level
- ➡ message contents

Parallelism





- Developed based on Intel TBB to Support event level parallelism
 - ⇒ Muster: Multiple SNiPER Task Scheduler
 - ⇒ SniperTbbTask: Binding of a SNiPER Task to a TBB task
 - Global DataStore to provide events for multi-tasks (or multi-threads)
 - A dedicated task(thread) is used to read/write event data from/to files

A typical Job configuration file

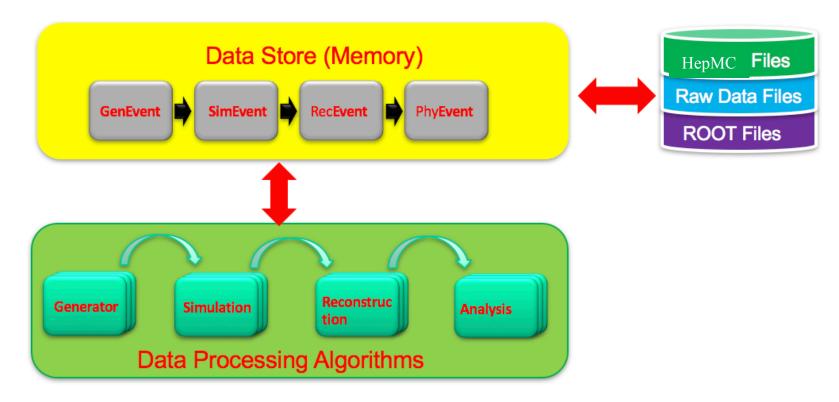


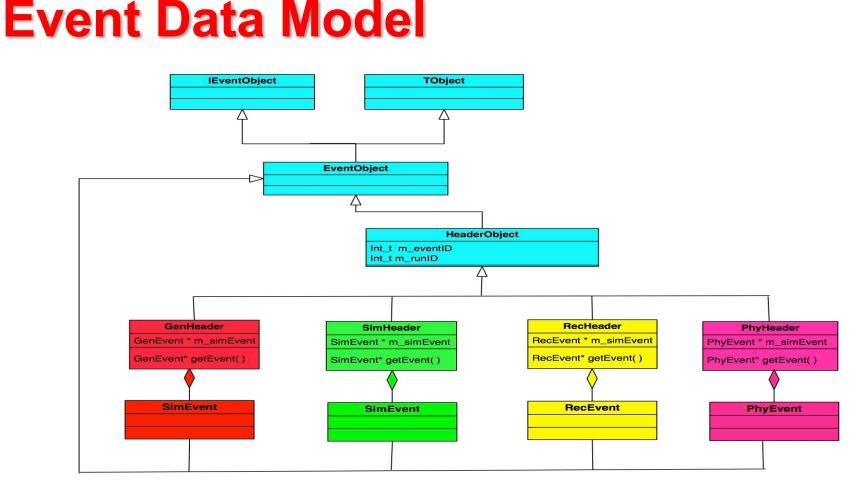
```
4 import Sniper
                                             Load the Library
 6 task = Sniper.Task("task")
                                             Setup a Task
 7 task.setLogLevel(3)
 8
9 import DetSimAlg
10 alg = task.createAlg("DetSimAlg/DetSimAlg")
                                            Add algorithm into the Task
11 alg.property("DetFactory").set("DemoFacory")
12
13 import OSCARSim
14 tool = alg.createTool("GeoAnaMgr/GeoAnaMgr")
                                             Define Detector Geometry
15 tool.property("Gdml2RootEnable").set(1)
16 tool.property("GdmlPath").set("/Event/DemoEvent")
17
18 import DataStoreMgr
                                             Define Event Manager
19 task.createSvc("DataStoreMgr")
20
21 import RootIOSvc
22 oSvc = task.createSvc("RootOutputSvc/OutputSvc") Output Event Data to Files
23 oSvc.property("OutputStream").set({"/Event/DemoEvent" : "DemoEvent.root"})
24
25 import G4Svc
                                            Set the Handler of Geant4
26 g4svc = task.createSvc("G4Svc/G4Svc")
27
28 import DemoSim
29 factory = task.createSvc("DemoSimFactory/DemoFacory")
30 factory.property("AnaMgrList").set(["DemoAnaMgr", "GeoAnaMgr"])
31
                       Define the number of Events to be proceed
32 task.setEvtMax(10)
33 task.show()
                                             Invoke running
34 task.run()
```

Event Data Model



- Definition of Event Information and correlation in different processing stages
- Key component and important for the software performance





- Event Objects are based on ROOT TObject
- One EDM both in memory and ROOT files to avoid conversion
- For each stage, Two-layer definition: HeaderObject and EventObject
- SmartRef for the correlation and supporting data-lazy loading

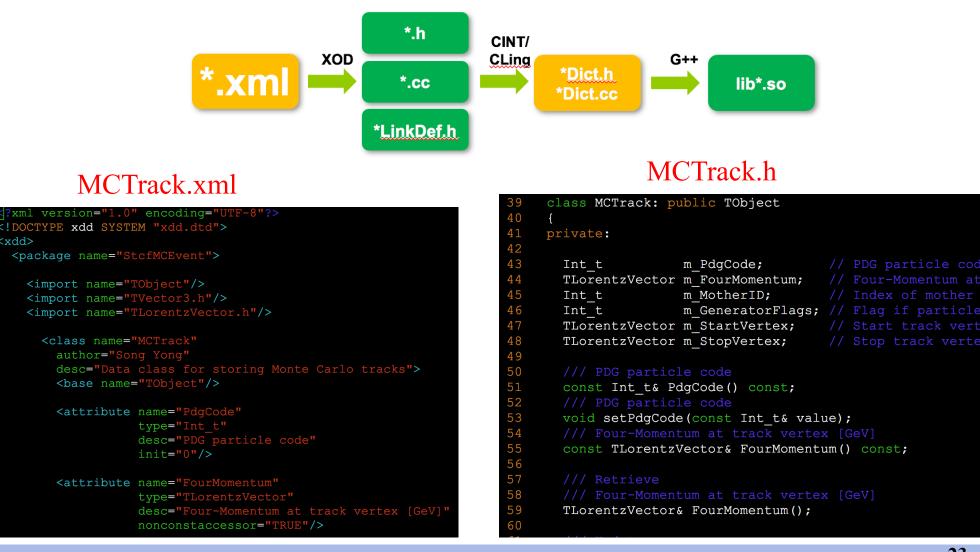
XOD: EDM Generation Toolkit

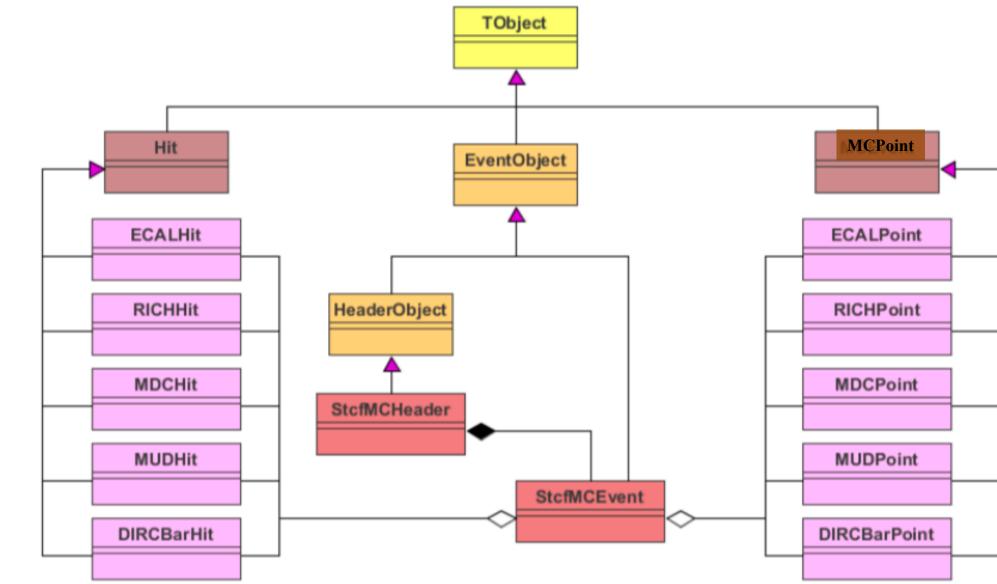


• Use XML file to define EDM

<xdd>

• XOD is developed to automatically generate class codes





MCEvent

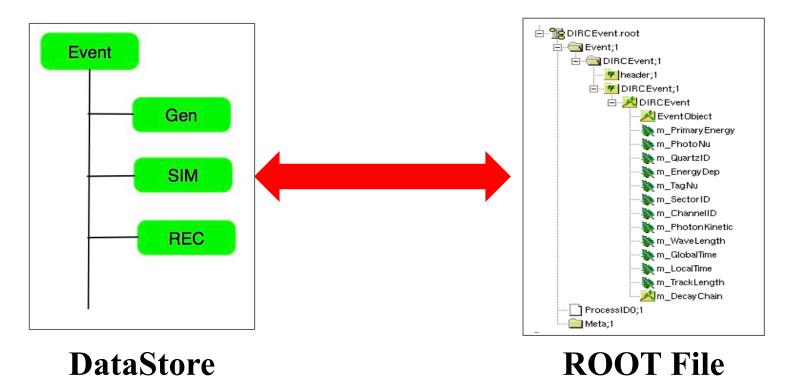


ROOT Input/Output System



General RootInputSvc/RootOutputSvc

- ➡ RootInputSvc: read Event Data from Root Files to Data Store
 - Correlation between header and event will automatically build up
- ⇒ RootOutputSvc: write Event Data from Data Store to Root Files
 - Root Files could be analyzed with root macro scripts
- ⇒ All Event data can be read/written automatically with current IO system



Generator

🔶 Babayaga

 $\Rightarrow e^+e^- --> e^+e^-, \mu^+\mu^-, \gamma\gamma \text{ and } \pi^+\pi^-$ QED processes at flavor factories

🔶 Phokhara

➡ e⁺e⁻ annihilation into hadrons plus an energetic photon from initial state radiation (ISR)

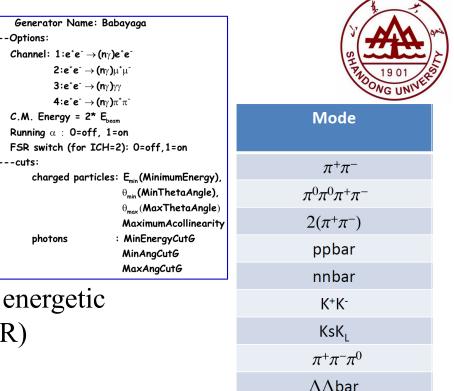
♦ KKMC

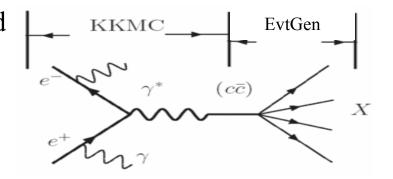
Charmonium production with beam spread and ISR

♦ EvtGen

⇒ Charmonium decays

Babayaga, Phokhara and KKMC are working in OSCAR EvtGen will be ready soon

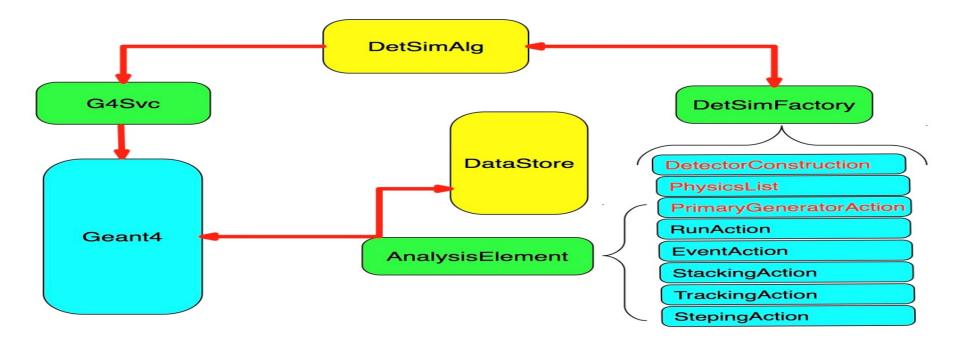




Detector Simulation Framework

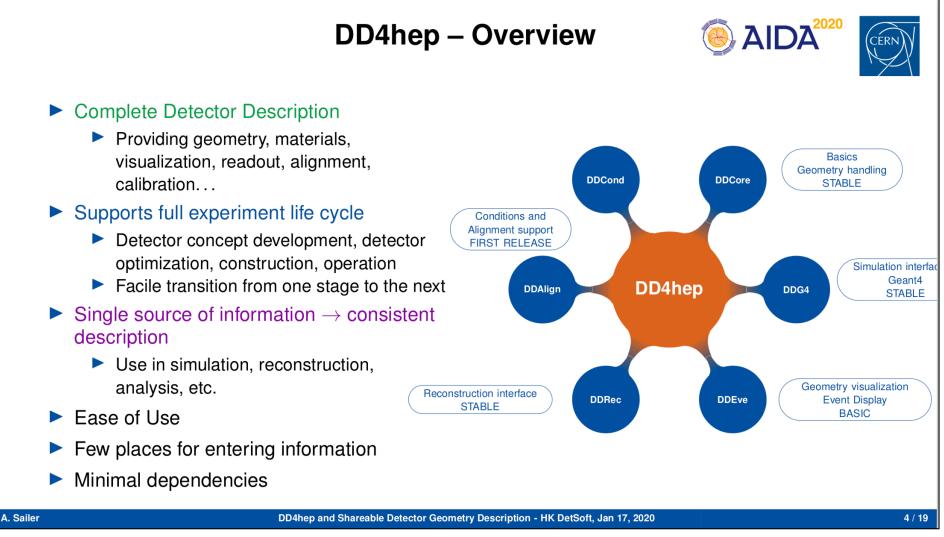


- OSCAR manages detector simulation with Task,
 - ⇒ The algorithm (**DetSimAlg**) for all sub-detectors simulation
 - ⇒ The service (**G4Svc**) to launch Geant4 within OSCAR
 - ⇒ The user-end service(**DetSimFactory**) to set up the Geant4 related classes
 - The user-end service(AnalysisElement) to retrieve G4Event and create Event Data in Data Store



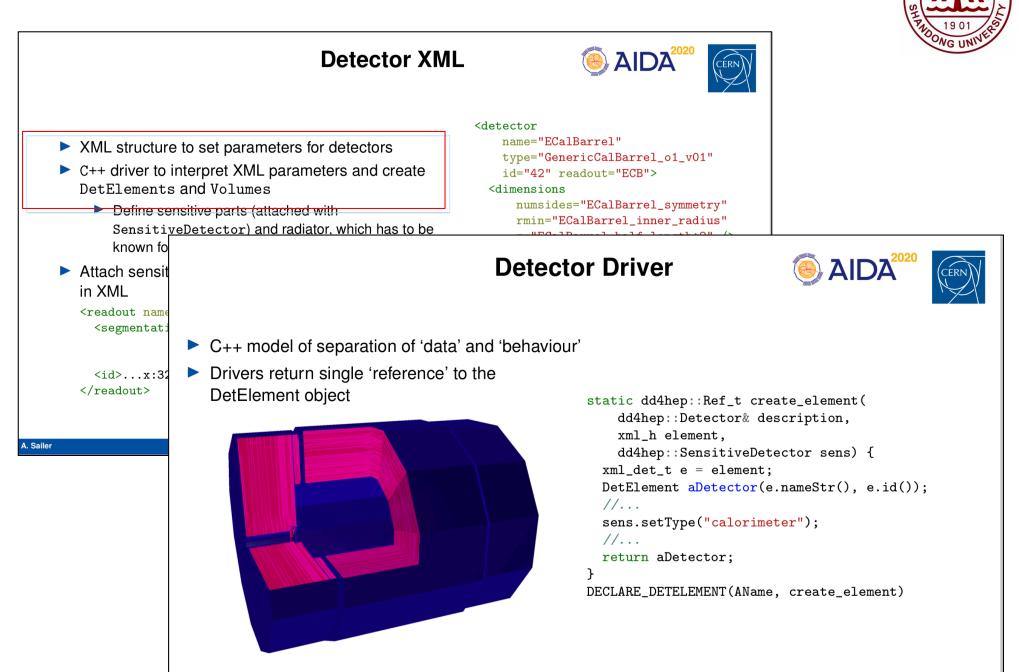
Detector Geometry Description :DD4hep





• Used by ILC and CLIC, FCC, CEPC, STCF and SCT ...

■ Use XML file and C++ driver to build Detectors



Detector Description with DD4hep



• Define geometry and materials in xml files

-bash-4.1\$ ls				
detectorDIRC.xml	detectorMUD.xml	detectorVTD.xml	materials01.xml	STCFECAL.xml
detectorECal.xml	detectorPID.xml	elements01.xml	materials02.xml	STCF_test.xml
detectorMDC.xml	detectorRICHBarrel.xml	elements02.xml	materials.xml	STCF.xml
detectorMUC.xml	detectorSC.xml	elements.xml	muondetector2.xml	

Construct detector in c++ driver files

-bash-4.1\$ ls AirTube_geo.cpp DIRC_geo.cpp SCTube_geo.cpp Tracker_geo.cpp BarrekDIRC_geo.cpp InnerPlanarTracker_geo.cpp STCF_BEMC_geo.cpp TrackerSupport_geo.cpp detectorMUD_cpp PolyhedraEndcapCalorimeter2_geo.cpp STCF_EEMC_geo.cpp ZPlanarTracker_geo.cpp

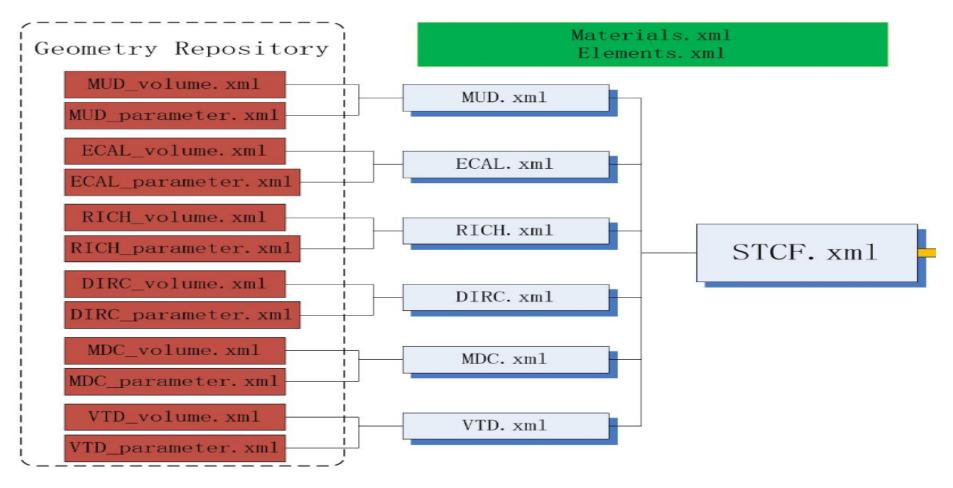
Deliver detector geometry to Geant4

import DetGeoConsSvc
myxmlsvc = task.createSvc("DetGeoConsSvc")
myxmlsvc.property("DetGeoConsSvcEnable").set(1)
myxmlsvc.property("GeoCompactFileName").set("/afs/ihep.ac.cn/soft
install/examples/ClientTests/compact/detectorSC.xml")

Detector Geometry Management



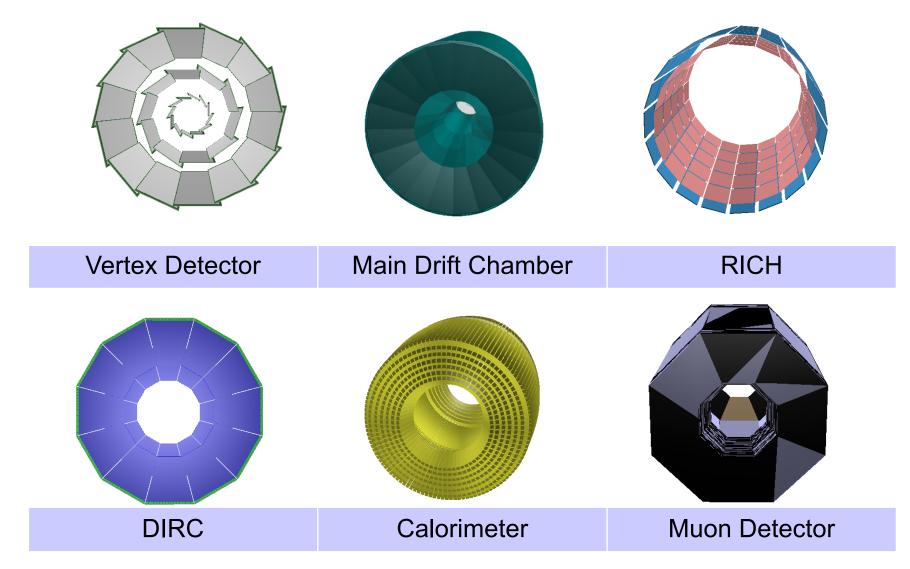
- Sub-detectors are described with DD4hep
- Each sub-detector is independent with others, different version in different path
- Flexible to build a full detector with different combinations of sub-detectors
- Common files for materials and elements



Detector Visualization

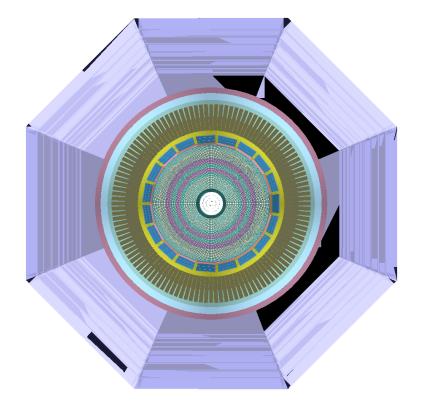


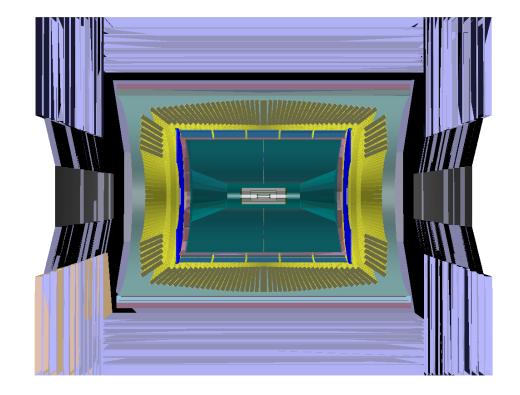
• Sub-detectors can be displayed individually with geoDisplay Plugin



Detector Visualization

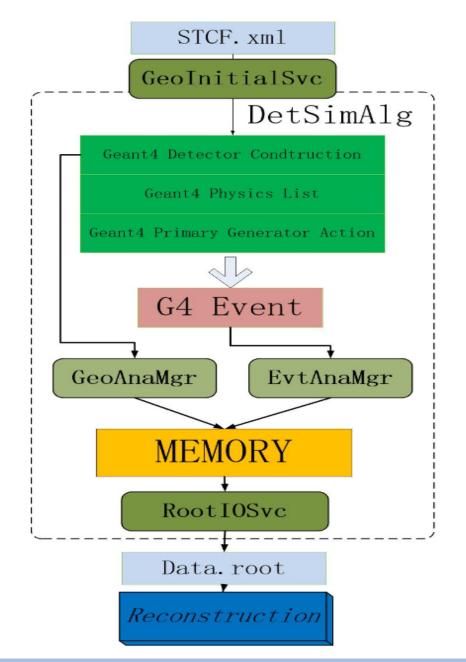




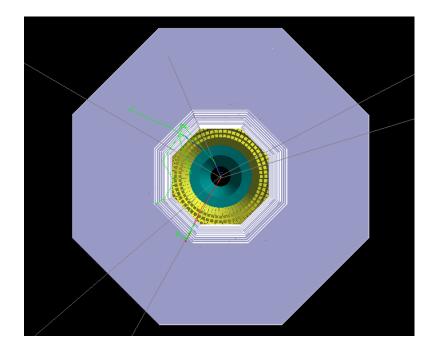


Set up Full Detector Simulation Chain





Display of a Event: e+ e- @Ecm =7GeV Geometry was initialized with DDG4 from xml file





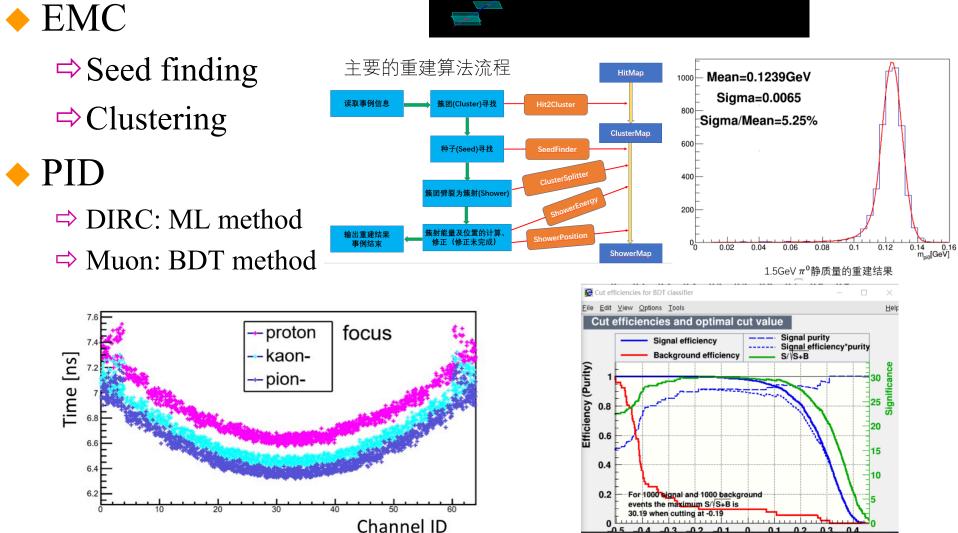
Reconstruction

⇒ Single tracking study

MDC

[ime [ns]





Installation, documentation and SVN



The latest version of OSCAR is installed in USTC nodes

- ⇒ stcf01.ustc.edu.cn
- ⇒ stcf01.ustc.edu.cn

Installation

- ⇒ Automatic installation of the whole offline software with a shell script
- ⇒ svn export <u>http://202.141.163.202/svn/oscar/installation/trunk/setup-trunkj.sh</u>

Documentation

- ➡ OSCAR User Guide
 - http://cicpi.ustc.edu.cn/indico/getFile.py/access?contribId=1&resId=0&materialId=slides&confId=1610



⇒ <u>http://202.141.163.202/svn/oscar/</u>

Summary and Outlook

OSCAR is developed for STCF

- ⇒ Based on SNiPER and DD4hep
- ⇒ Event Data Management
- ⇒ Data proceeding management
- ⇒ Common Services and User interface
- ⇒ Serve as the unifed platform for application development

Lots of progress have be made

- ⇒ Generators: Babayaga, Phokhara and KKMC
- ⇒ Detector geometry description with DD4hep: modular and flexible
- ⇒ Detector geometry management: Xml->Geant4-> ROOT->Recon.
- ⇒ Event data model: currently based on ROOT
- ⇒ Root Input/Output System
- ⇒ The detector simulation chain has been setup
- ⇒ Development of reconstruction algorithms is in progress



Summary and Outlook



Lots of works ahead, more people are welcome

- ⇒ Event Data Model for Simulation and Reconstruction
- ⇒ Generator framework: More generators and Unified interface
- ➡ Optimize detector description:
 - Missing parts, precision description, digitization and realization
- ➡ Study of Calibration and Reconstruction methods
- ➡ Compare sub-detector performances between simulation and beam testing.

Setup a full chain from generator to reconstruction for optimization of Detector design and performance study.

- ➡ Tracking efficiency
- ⇒ Energy, Momentum, position resolutions
- ➡ Discrimination of electron/pion, muon/pion, kaon/pion

Keep eyes on the new development of the community

- ⇒ DD4hep: common Detector Description (already used by STCF)
- ⇒ EDM4hep: common Event Data Model (STCF prototype for testing)
- ⇒ Key4hep: common Software Stack

Thanks for your attention!